HPdesign: Inverse Folding of Proteins



Albert-Ludwigs-University Freiburg

Martin Mann and Sebastian Will and Rolf Backofen

Albert-Ludwigs-University Freiburg · Inst. of Computer Science · Chair for Bioinformatics Georges-Köhler-Allee 106 · 79110 Freiburg · Germany

{mmann,will,backofen}@informatik.uni-freiburg.de http://www.bioinf.uni-freiburg.de/sw/cpsp/



Chair for Bioinformatics Computer Science

Introduction

Sequence design is a neccessary tool for the investigation of sequence-structure relations. Insights into such fundamental properties will aid to understand protein folding, their evolution, and drug design. The HP-model by Lau and Dill [1] mimics globular watersoluble proteins. It is lattice based and focuses on hydrophobic forces. Even in this coarse-grained model, structure prediction and sequence design is NP-complete [2]. Nevertheless, Backofen and Will introduced a Constraintbased Protein Structure Prediction (CPSP) approach [3] 3D Lattice protein that allows the enumeration of all optimal structures.

candidate sequence S in S. This procedure yields a set of sequences S that can adopt \mathcal{L} with a low energy and have high chance to form \mathcal{L} as an optimal structure. The number of optimal H-cores is still exponential in the core size but increases much slower than the number of possible sequences (see Fig. 3).

Number of H-cores vs. size

Growth of possible sequences and H-cores







HPdesign uses the CPSP approach to solve the inverse folding problem for threedimensional lattices. Here, a sequence X is searched that adopts a given structure S as its single optimal one.

Preliminaries

Energy and Optimality of a Structure: The contact *energy* in the HP-Model is the negated sum over all non-successive H-monomer contacts. A structure with minimal energy (i.e. maximal H-H contacts) is called *optimal* and has usually a globular shape as in nature [4].

H-cores: The placing of the H-monomers in a structure is called *H-core* [3]. For a fixed sequence, the energy is completely determined by the H-core internal contacts. This is visualized in Fig. 1 by two structures with energy -3 and -1(left/right) and the corresponding H-core with 4 contacts. The optimal H-cores are independent of a concrete sequence and can be precalculated in advance [3].



Figure 3: Number of (sub-)optimal H-cores v.s size and the growth vs. # of possible sequences.

An example illustrating the first step is given in Fig. 2. Here, the H-core of Fig. 1 can be mapped in three ways on the given structure and yields three different candidate sequences.

Step 2 : Sequence Filtering

CPSP: The Constraint-based Protein Structure Prediction (CPSP) approach [3] allows the optimal structure enumeration of 3D lattice proteins using Constraint Programming methods.

Given a sequence S with k H's: For each H-core \mathcal{H} of size k a CSP is formulated that constrains the monomer sequence S to form a selfavoiding-walk in the lattice, placing all H-monomers on positions in \mathcal{H} . Starting with the optimal H-cores, this iterative process ensures optimality and allows further the complete enumeration of all optimal structures.

Filtering: To check each candidate sequences $S \in \mathcal{S}$ of step 1 to be proteinlike and to form the given structure stable we enumerate up to 2 optimal structures of S (CPSP). If there is only one, S forms only one stable structure \mathcal{L}' and we check if $\mathcal{L}' \equiv \mathcal{L}$. If S fullfills both criteria it is reported otherwise rejected.



Figure 1: Lattice protein structures and the corresponding H-core.

Protein-like Sequences: In contrast to random sequences proteins adopt only one stable optimal structure. Therefore for simplicity, HP-sequences are regarded *protein-like* only if they have exactly one (or only a few) optimal structure [5].

Method

The algorithm is a Generate-and-Test method that allows, in contrast to existing methods [6, 7], a systematic and complete enumeration of target sequences within user defined limits. First, a good set of candidate sequences is generated that have a high chance to form the given structure as an optimal one. Afterwards, these sequences are checked if this is true and if they are protein-like.

Step 1 : Candidate Set Generation

In the HP-model, the number of possible sequences $S \in \mathcal{S}$ for a given structure \mathcal{L} is 2^N . To enable a Generate-and-Test approach we have to keep the number of sequences to test as small as possible.

In HPdesign, this is done using a database of (sub-)optimal H-cores. As visible in Fig. 1, the placing of an H-core into a given structure determines a sequence. Following the constraint, that the sequences have to form \mathcal{L} as optimal structure, we use optimal H-cores for sequence generation.

Conclusion



The presented method HPdesign is the first exact method that solves the Inverse Folding Problem for 3D lattice proteins in the HP-model. Using HPdesign one can generate HP-sequences that adopt a given structure as their optimal one. Further the number of optimal structures they can adopt, an important measure for protein-like sequences, can be constrained. FCC structure

The Generate-and-Test approach is based on a precalculated database of optimal and suboptimal H-cores and the fast and exact CPSP-method by Backofen and Will [3]. It is currently implemented using the cubic and more complex face-centered-cubic (FCC) lattice (see figure).

The free CPSP-tools package including HPdesign and other tools is accessible at

http://www.bioinf.uni-freiburg.de/sw/cpsp/

References

[1] Kit Fun Lau and Ken A. Dill. *Macromolecules*, 22:3986–3997, 1989. [2] William E. Hart. In *RECOMB*, pages 128–136, 1997.



Figure 2: Different matches and derived sequences for a structure and the H-core in Fig. 1.

For each arbitrary optimal H-core \mathcal{H} we shift the core through \mathcal{L} . If all positions of \mathcal{H} can be mapped to positions of \mathcal{L} a match is found and we store the resulting [3] Rolf Backofen and Sebastian Will. Constraints, 11(1):5 - 30, 2006.

- [4] Christian B. Anfinsen. Principles that govern the folding of protein chains. Science, 181(96):223–230, July 1973.
- [5] B. P. Blackburne and J. D. Hirst. Three-dimensional functional model proteins: Structure function and evolution. JCP, 119:3453–3460, August 2003.
- [6] B. S. Sanjeev, S. M. Patra, and S. Vishveshwara. Journal of Chemical Physics, 114:1906– 1914, 2001.
- [7] K. Yue, K. M. Fiebig, P. D. Thomas, H. S. Chan, E. I. Shakhnovich, and K. A. Dill. Proc. Natl. Acad. Sci. USA, 92(1):325–9, 1995.

Acknowledgments

Martin Mann is supported by the EU project EMBIO (EC contract number 012835)